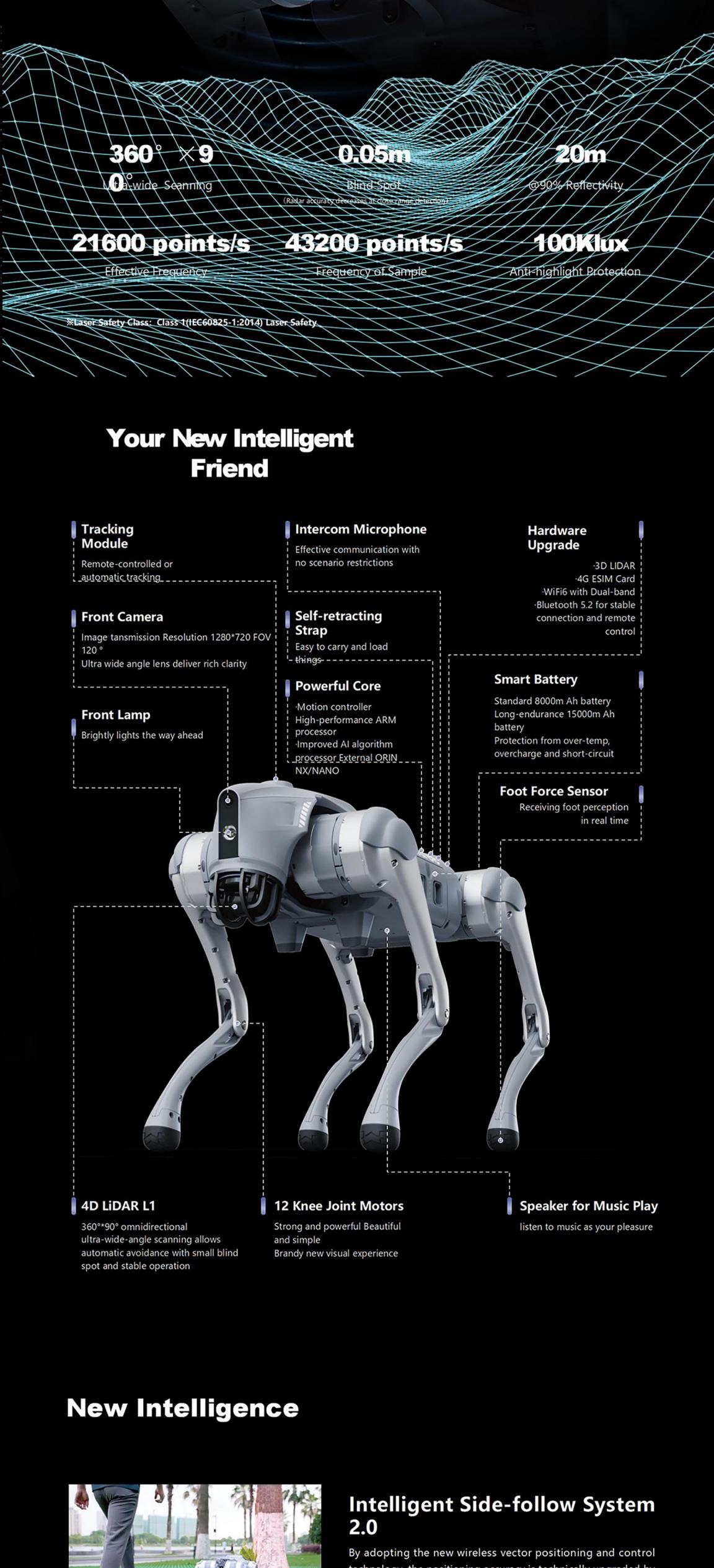
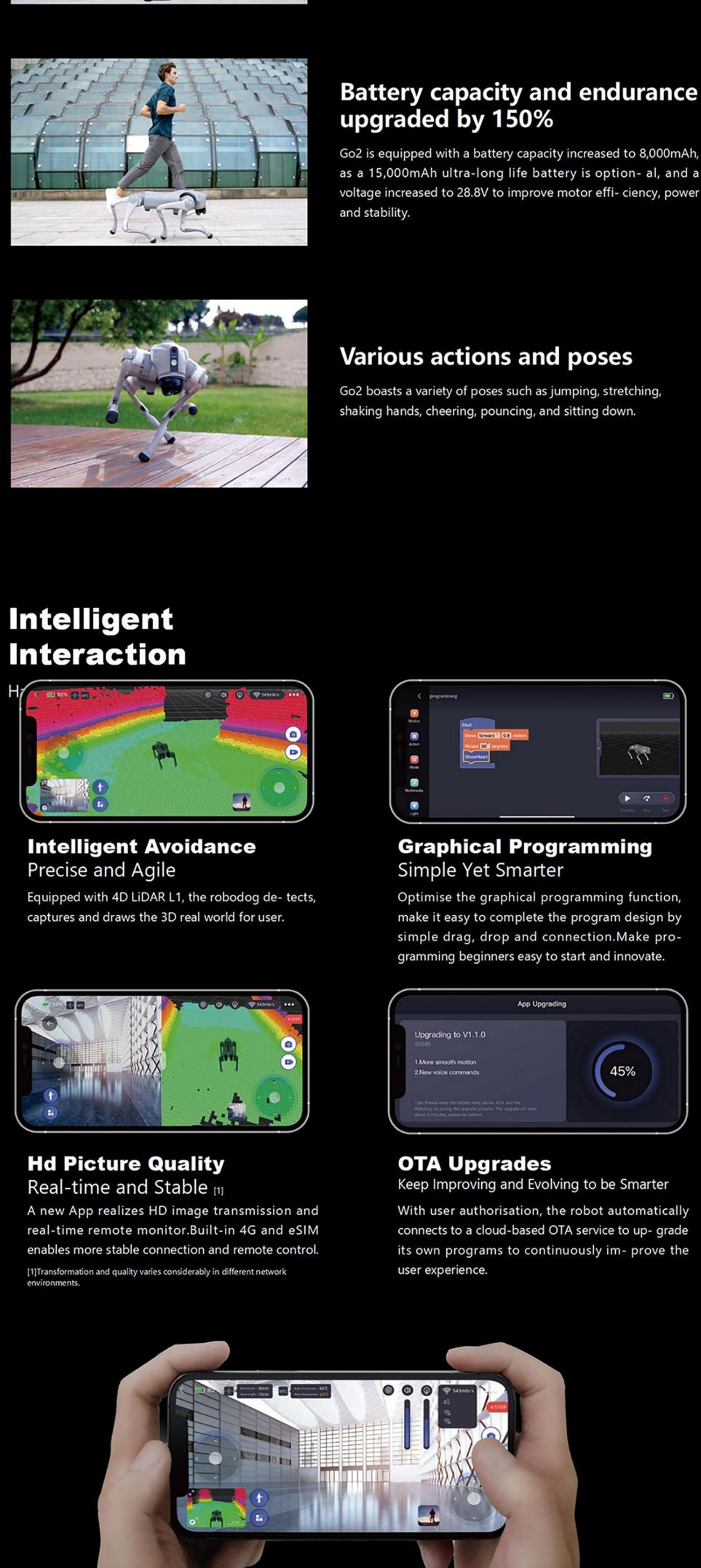


Standard Ultra-wide 4D LiDAR Upgrades Recognition System by 200%

Features with Unitree's self-developed 4D LiDAR L1 with 360° x 90° hemispherical ultra-wide recognition, super small blind spot and a minimum detection distance as low as 0.05m, which makes realize all-terrain recognizing.



Your New Intelligent Friend



New Intelligence



Intelligent Side-follow System 2.0

By adopting the new wireless vector positioning and control technology, the positioning accuracy is technically upgraded by 50%, the remote control distance is over 30m^[1], and combined with the optimised obstacle avoidance strategy, it can make the robot better traverse complex terrain.

[1] In open spaces with no shelter



Motor performance enhanced by 30%

Go2 boasts a peak joint torque of 45N.m^[2], a new internal trace connecting technique, and heat pipe coolers to decrease temperature effectively.

[2] The maximum torque in the table refers to the maximum torque of the largest joint motor; the actual maximum torque varies for the 12 joint motors.



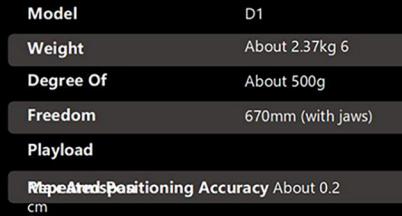
Battery capacity and endurance upgraded by 150%

Go2 is equipped with a battery capacity increased to 8,000mAh, as a 15,000mAh ultra-long life battery is option^{-al}, and a voltage increased to 28.8V to improve motor efficiency, power and stability.

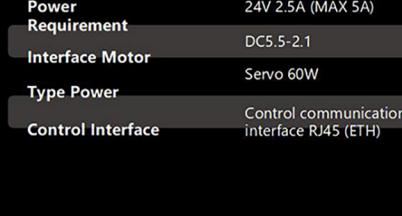


Various actions and poses

Go2 boasts a variety of poses such as jumping, stretching, shaking hands, cheering, poses such as jumping, stretching, shaking hands, cheering, pouncing, sitting, downing.



Intelligent Interaction



Intelligent Avoidance

Precise and Agile. Equipped with 4D LiDAR L1, the robot can detect, capture and draw the 3D real world for user to see.

Graphical Programming

Simple Yet Smarter. Optimize the graphical programming function, simple drag, drop and connection. Make programming beginners easy to start and innovate.

Hd Picture Quality

Real-time and Stable. A new App realizes HD image transmission and real-time remote monitor. Built-in 4G and eSIM enables more stable connection and remote control.

environments.

OTA Upgrades

Keep Improving and Evolving to be Smarter. With user authorisation, the robot automatically connects to a cloud-based OTA service to upgrade its own programs to continuously improve the user experience.

D1 Servo Mechanical Arm

Model: D1. Weight: About 2.37kg. Degree Of Freedom: About 500g.

Freedom: 670mm (With Jaws). Payload: About 0.2kg.

Repeatability Position Accuracy: About 0.12mm. Power: 24V 2.5A (MAX 5A).

Requirement: DC5.5-20V. Interface Motor: Servo 5.0V.

Type Power: Control communication. Control Interface: Interface RJ45 (ETH).

Docking Station

Model: MID-360. Size (Without bracket): 65mm*65mm*60mm. Voltage: 9-27V DC. Power: 905mW.

Range: Horizontal 360°, Vertical 7°-52°. Laser wavelength: 808nm. FOV: (-15°~+15°).

Computing power: Up to 100Tops. Interface: Gigabit Ethernet (GH1.25-4PIN) X1, 10GbE Port (GH1.25-4PIN) X1, M8Gb Port (GH1.25-4PIN) X1.

Expansion: 16-60V DC. Interface: USB3.0 Type-C X1, USB2.0 Type-C X1, USB2.0 Type-A X1.

Power: Nano 800mW, Orin NX 16GB. Interface: M8Gb Port (GH1.25-4PIN) X1.

Remote Controller (screen+cameras)

Number of Camera: 2. Resolution: 1920*1080. Frequency: 2.4GHz.

Wireless: 30W. Power: Red and blue sharp flash.

Searchlight: MK15. Power: 30W.

Power: Alarm light: 30W.

Extensions

Model: MID360. Size (Without bracket): 65mm*65mm*60mm. Voltage: 9-27V DC. Power: 905mW.

Range: Horizontal 360°, Vertical 7°-52°. Laser wavelength: 808nm. FOV: (-15°~+15°).

Computing power: Up to 100Tops. Interface: Gigabit Ethernet (GH1.25-4PIN) X1, 10GbE Port (GH1.25-4PIN) X1, M8Gb Port (GH1.25-4PIN) X1.

Expansion: 16-60V DC. Interface: USB3.0 Type-C X1, USB2.0 Type-C X1, USB2.0 Type-A X1.

Power: Nano 800mW, Orin NX 16GB. Interface: M8Gb Port (GH1.25-4PIN) X1.

Model: MID-360. Size (Without bracket): 65mm*65mm*60mm. Voltage: 9-27V DC. Power: 905mW.

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